CLAIM

1. A part positioning method in which a part supported by a self-traveling machine is positioned with respect to a part fitting object, comprising the steps of:

setting on said part fitting object an engaging means provided on a tip end of a wire member which is possible to be pulled out and wound up;

detecting a pulled-out length and an existing location of said wire member and moving said self-traveling machine to eliminate relative positional discrepancies between said part fitting object and the part;

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fitting the part to said part fitting object in the state that the positional discrepancies are eliminated; and

after fitting the part to said part fitting object, removing and retrieving said engaging means from said part fitting object.

2. A part positioning apparatus for positioning a part supported by a self-traveling machine with respect to a part fitting object, comprising:

an engaging means being provided on a tip end of a wire member so as to be set on said part fitting object;

- a sensed member for accommodating said wire member in such a state as to be pulled out and wound up;
 - a first sensor for detecting a pulled-out length of said wire member when said engaging means is set on said part fitting object;
 - a second sensor for detecting an existing location of said wire member when said engaging means is set on said part fitting object; and
- a controller means for controlling a traveling amount of said self-traveling machine such that each of detection values of said first sensor and said second sensor is in agreement with a reference value.